

线性变换  
方法如P11

中国科学技术大学 2018-2019 学年第二学期  
线性代数 (B1) 期末考试

1. (5分)  $\alpha = (1, 2, 3)^T$  是矩阵  $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$  的特征向量, 求  $A^2 \alpha$  的值.

(1) 若  $\alpha_1, \alpha_2, \alpha_3$  是  $\mathbb{R}^3$  的一组基, 则由  $\alpha_1, \alpha_2, \alpha_3$  到  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  的过渡矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

(2) 若  $\alpha^T$  上的线性变换  $\sigma$  在基  $\alpha_1, \alpha_2, \alpha_3$  下的矩阵为  $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ , 则  $\sigma$  在基  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  下的矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

(3) 若矩阵  $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$  的特征向量  $\alpha = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ , 则  $x = \_, y = \_$ .

(4) 若  $\alpha_1, \alpha_2, \alpha_3$  是  $\mathbb{R}^3$  的一组基,  $\alpha_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \alpha_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \alpha_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ , 则由  $\alpha_1, \alpha_2, \alpha_3$  到  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  的过渡矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

(5) 若二次型  $Q(x, y, z) = x^2 + 2y^2 + 3z^2 + 2xy + 2xz + 2yz - 1$  的正惯性指数为  $\_$ .

2. (15分)  $\alpha = (1, 2, 3)^T$  是矩阵  $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$  的特征向量, 求  $A^2 \alpha$  的值.

(1) 若  $\alpha_1, \alpha_2, \alpha_3$  是  $\mathbb{R}^3$  的一组基, 则由  $\alpha_1, \alpha_2, \alpha_3$  到  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  的过渡矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

(2) 若  $\alpha^T$  上的线性变换  $\sigma$  在基  $\alpha_1, \alpha_2, \alpha_3$  下的矩阵为  $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ , 则  $\sigma$  在基  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  下的矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

(3) 若  $\alpha_1, \alpha_2, \alpha_3$  是  $\mathbb{R}^3$  的一组基,  $\alpha_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \alpha_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \alpha_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ , 则由  $\alpha_1, \alpha_2, \alpha_3$  到  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  的过渡矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

(4) 若  $\alpha^T$  上的线性变换  $\sigma$  在基  $\alpha_1, \alpha_2, \alpha_3$  下的矩阵为  $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ , 则  $\sigma$  在基  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  下的矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

(5) 若  $\alpha_1, \alpha_2, \alpha_3$  是  $\mathbb{R}^3$  的一组基,  $\alpha_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \alpha_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \alpha_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ , 则由  $\alpha_1, \alpha_2, \alpha_3$  到  $\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1$  的过渡矩阵为  $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

$A(x, y, z) = (\lambda x, \mu y, \nu z)$  在  $\alpha^T$  下的矩阵

$A(\vec{e}_1) = A \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \lambda \\ 0 \\ 0 \end{pmatrix} \quad A = \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \mu & 0 \\ 0 & 0 & \nu \end{pmatrix}$

$A(\vec{e}_2) = \begin{pmatrix} 0 \\ \mu \\ 0 \end{pmatrix}$

$A(\vec{e}_3) = \begin{pmatrix} 0 \\ 0 \\ \nu \end{pmatrix}$

做内积在  $P_1, P_2$  上

$A(x_1, x_2, \dots, x_n) = (x_1, x_2, \dots, x_n) \begin{pmatrix} \lambda & & & \\ & \mu & & \\ & & \ddots & \\ & & & \nu \end{pmatrix}$

$\alpha \begin{pmatrix} 0 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & 1 & 0 \\ 3 & 0 & -1 \end{pmatrix}$

$A(x_1, x_2, x_3) = (x_1, x_2, x_3) A = (P_1, P_2, P_3)$

所以  $P^{-1} A P = \Lambda = \text{diag}(\lambda, \mu, \nu)$

$A(x_1, x_2, x_3) = A((x_1, x_2, x_3) \cdot \alpha^{-1}) = A(x_1, x_2, x_3) \cdot \alpha^{-1}$

$\tilde{A} = P^{-1} A P = \Lambda = \text{diag}(\lambda, \mu, \nu)$

$A = P \tilde{A} P^{-1} = P \Lambda P^{-1}$

1. (1)  $\begin{pmatrix} 1 & 0 & 1 \\ 2 & 2 & 0 \\ 0 & 3 & 3 \end{pmatrix}$

$(\alpha_1, \alpha_2, \alpha_3) = (\alpha_1, \alpha_2, \alpha_3) \begin{pmatrix} 1 & & \\ & 2 & \\ & & 3 \end{pmatrix}$

$(\alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_1) = (\alpha_1, \alpha_2, \alpha_3) \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$

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基底变换  $G, g_j = (\alpha_i, \beta_j)$

$\alpha - \alpha_1$  线性变换  $\Rightarrow \det G \neq 0$

反证

假设  $\alpha_1 = 0, \alpha_2 \neq 0$

和  $\alpha_1, \alpha_2$  线性,  $g_j \alpha_1 = 0$  非零

基底之间的正交基  $S = (\alpha_1, \dots, \alpha_n)$

$\rightarrow$  标准正交基  $(\alpha_1, \dots, \alpha_n)$

$P$  是正交三角阵

$\alpha: S$  的基底变换  $G$

$\rightarrow P^T G P = \Lambda$  (相似)

$S, T$  都是正交阵, 基底变换  $G$

$S = T P, P^T P = I, P = P^T$

基底变换  $P$

$A = \begin{pmatrix} (\alpha_1, \alpha_2) & \dots & (\alpha_{n-1}, \alpha_n) \\ \vdots & & \vdots \\ (\alpha_n, \alpha_1) & \dots & (\alpha_n, \alpha_n) \end{pmatrix}$

$A = \begin{pmatrix} (\alpha_1, \alpha_2) & \dots & (\alpha_{n-1}, \alpha_n) \\ \vdots & & \vdots \\ (\alpha_n, \alpha_1) & \dots & (\alpha_n, \alpha_n) \end{pmatrix}$