

# 课后题

2022年3月6日 星期日 下午4:23

1.  $E_{11} = \frac{Q}{2\epsilon_0}, E_{12} = \frac{Q}{2\epsilon_0}$   
 $E_{21} = \frac{Q}{2\epsilon_0}, E_{22} = \frac{Q}{2\epsilon_0}$

板内电场恒为0.  $E_{11} = E_{12} + E_{21} + E_{22}$   
 $E_{22} = E_{11} + E_{12} + E_{21}$

2.  $E_1 \times 4\pi R_1^2 = \frac{Q}{\epsilon_0}, \vec{E}_1 = \frac{Q}{4\pi R_1^2 \epsilon_0}$   
 $\int_{R_1}^{\infty} \frac{Q}{4\pi r^2 \epsilon_0} dr = \frac{Q}{4\pi \epsilon_0} \left[ -\frac{1}{r} \right]_{R_1}^{\infty} = \frac{Q}{4\pi \epsilon_0 R_1}$

$dQ = \frac{Q}{4\pi(R_2^2 - R_1^2)} d(4\pi R^2) d\theta$   
 $= \frac{3Q R dR}{2(R_2^2 - R_1^2 + 2R^2)}$

$dU = \frac{1}{4\pi \epsilon_0} \frac{dQ}{R} = \frac{3Q R dR}{4\pi \epsilon_0 (R_2^2 - R_1^2 + 2R^2)}$   
 $U_1 = \frac{3Q}{4\pi \epsilon_0} \int_{R_1}^{R_2} \frac{R dR}{R_2^2 - R_1^2 + 2R^2}$

$U_{12} + U_{22}, U_{12} = \frac{Q}{4\pi \epsilon_0} \frac{Q}{R_2 - R_1} = \frac{3Q R_1 (R_2 + R_1)}{4\pi \epsilon_0 (R_2^2 - R_1^2 + 2R_1 R_2)}$

3.  $pAS + 2 \int_C \rho_s \frac{Q}{\epsilon_0} = pAS + 10\pi R^2$   
 $\vec{E} = p \vec{e}_r - 2\pi R^2 \vec{e}_r$

$F = 2\alpha \times 2\pi R = 4\alpha \pi R$   
 $F_{\vec{e}_r} = \int p ds \cos\theta$   
 $= \int_0^{\pi} \int_0^{2\pi} p R^2 \sin\theta d\theta d\phi \cos\theta$   
 $= 2\pi R^2 \int_0^{\pi} p \cos\theta \sin\theta d\theta = 2\pi R^2 p$

4.  $U_{ab} = \dots$

5.  $E_1 = \frac{Q}{4\pi R_1^2 \epsilon_0}, E_2 = \frac{Q}{4\pi R_2^2 \epsilon_0}$   
 $0 > 2\pi R_1^2 = \frac{Q}{2\epsilon_0} + \sigma_1 \times 4\pi R_1^2, \sigma_1 = \frac{Q}{4\pi R_1^2}, \sigma_2 = -\frac{Q}{4\pi R_2^2}$

$F_1 = \frac{Q_1 Q_2}{4\pi R_1^2} \vec{r}_1 + \frac{Q_1 Q_2}{4\pi R_2^2} \vec{r}_2, \vec{W} = \vec{F} \cdot \vec{r}$

b.  $C_1 = \frac{Q}{V} = \frac{\sigma S}{\frac{\sigma S}{\epsilon_0}} = \frac{\sigma S}{\frac{\sigma S}{\epsilon_0}} = \frac{\epsilon_0 S}{d}$   
 $C_2 = \frac{Q}{V} = \frac{\sigma S}{\frac{\sigma S}{\epsilon_0} + \frac{\sigma S}{\epsilon_0}} = \frac{\epsilon_0 S}{2d}$   
 $C = C_1 + C_2 = \frac{2\epsilon_0 S}{d}$

7.  $C_1 = \frac{Q}{V} = \frac{2\sigma S}{d}$   
 $C_2 = C_1 = \frac{2\sigma S}{d}$   
 $C = \frac{4\sigma S}{d}$

8.  $\vec{E} = \dots$

9.  $\vec{E} = \dots$

10.  $\dots$

11.  $\vec{E} = \dots$

12.  $\vec{E} = \dots$

13.  $\vec{E} = \dots$

14.  $\vec{E} = \dots$

15.  $\vec{E} = \dots$

16.  $\vec{E} = \dots$

17.  $\vec{E} = \dots$

18.  $\vec{E} = \dots$

19.  $\vec{E} = \dots$

20.  $\vec{E} = \dots$

21.  $\vec{E} = \dots$

22.  $\vec{E} = \dots$

1.  $E_S = \frac{\sigma S}{\epsilon_0}, E = \frac{\sigma}{\epsilon_0}$

$\vec{E}_1 \cdot \vec{E}_2 = \frac{(\sigma_1 + \sigma_2) S}{\epsilon_0}, \sigma_2 = -\sigma_1$

取正电荷为J.  $\frac{\sigma_1}{\epsilon_0} - \frac{\sigma_2}{\epsilon_0} = \frac{\sigma_1 - \sigma_2}{\epsilon_0} > 0$

$\sigma_1, \frac{\sigma_1}{\epsilon_0} + \frac{\sigma_2}{\epsilon_0} = \frac{\sigma_1 - \sigma_2}{\epsilon_0} > 0$

$\sigma_1 = \sigma_2$

2.  $\sigma_1 S - \sigma_2 S = Q_1 \Rightarrow \sigma_1 S - \sigma_2 S = 0$   
 $\sigma_1 S + \sigma_2 S = Q_2 \Rightarrow -\sigma_2 S + \sigma_1 S = Q_2$   
 $\sigma_1 = \frac{Q_1 + Q_2}{2S} = \sigma_2, \sigma_2 = \frac{Q_1 - Q_2}{2S} = \sigma_3$

3.  $0 < r < R_1, \vec{E}_1 = \dots$   
 $R_1 < r < R_2, \vec{E}_2 = \frac{Q}{4\pi r^2 \epsilon_0}$   
 $R_2 < r < R_3, \vec{E}_3 = 0$   
 $r > R_3, \vec{E}_4 = \frac{Q + Q'}{4\pi r^2 \epsilon_0}$

内球电荷为0. 故无正电荷.  $\int_{R_1}^{R_2} \vec{E}_2 \cdot d\vec{l} + \int_{R_2}^{R_3} \vec{E}_3 \cdot d\vec{l} = 0$

$\int_{R_1}^{R_2} \frac{Q}{4\pi r^2 \epsilon_0} dr + \int_{R_2}^{R_3} \frac{Q}{4\pi r^2 \epsilon_0} dr = 0$

$-Q \left( \frac{1}{R_1} - \frac{1}{R_2} + \frac{1}{R_2} - \frac{1}{R_3} \right) = Q \left( \frac{1}{R_1} - \frac{1}{R_2} \right)$

$Q \left( \frac{1}{R_1} - \frac{1}{R_2} + \frac{1}{R_2} - \frac{1}{R_3} \right) = Q \left( \frac{1}{R_1} - \frac{1}{R_2} \right)$

$Q \left( \frac{1}{R_1} - \frac{1}{R_2} + \frac{1}{R_2} - \frac{1}{R_3} \right) = Q \left( \frac{1}{R_1} - \frac{1}{R_2} \right)$

球壳电荷:  $\frac{Q_1 Q_2}{4\pi R_1 R_2} \int_{R_1}^{R_2} \frac{1}{r} dr$

$= \frac{Q_1 Q_2}{4\pi R_1 R_2} \left( \ln \frac{R_2}{R_1} \right)$

$= \frac{1}{4\pi \epsilon_0} \frac{Q_1 Q_2}{R_1 R_2} \ln \frac{R_2}{R_1}$

$= \frac{1}{4\pi \epsilon_0} \frac{Q_1 Q_2}{R_1 R_2} \ln \frac{R_2}{R_1}$

4.  $\vec{E} = \dots$

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